

MPI for Python

<http://mpi4py.scipy.org>

Lisandro Dalcin
dalcinl@gmail.com

Centro Internacional de Métodos Computacionales en Ingeniería
Consejo Nacional de Investigaciones Científicas y Técnicas
Santa Fe, Argentina

January, 2011
Python for parallel scientific computing
PASI, Valparaíso, Chile

Outline

Overview

Communicators

Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

Overview

Communicators

Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

What is mpi4py?

- ▶ Full-featured Python bindings for **MPI**.
- ▶ API based on the standard MPI-2 C++ bindings.
- ▶ Almost all MPI calls are supported.
 - ▶ targeted to MPI-2 implementations.
 - ▶ also works with MPI-1 implementations.

Implementation

Implemented with **Cython**

- ▶ Code base far easier to write, maintain, and extend.
- ▶ Faster than other solutions (mixed Python and C codes).
- ▶ A *pythonic* API that runs at C speed !

Features – MPI-1

- ▶ Process groups and communication domains.
 - ▶ intracomunicators
 - ▶ intercommunicators
- ▶ Point to point communication.
 - ▶ blocking (send/recv)
 - ▶ nonblocking (isend/irecv + test/wait)
- ▶ Collective operations.
 - ▶ Synchronization (barrier)
 - ▶ Communication (broadcast, scatter/gather)
 - ▶ Global reductions (reduce, scan)

Features – MPI-2

- ▶ Dynamic process management (spawn, connect/accept).
- ▶ Parallel I/O (read/write).
- ▶ One sided operations, a.k.a. RMA (put/get/accumulate).
- ▶ Extended collective operations.

Features – Python

- ▶ Communication of Python objects.
 - ▶ high level and very convenient, based in pickle serialization
 - ▶ can be slow for large data (CPU and memory consuming)

```
<object> —> pickle.dump() —> send()
```

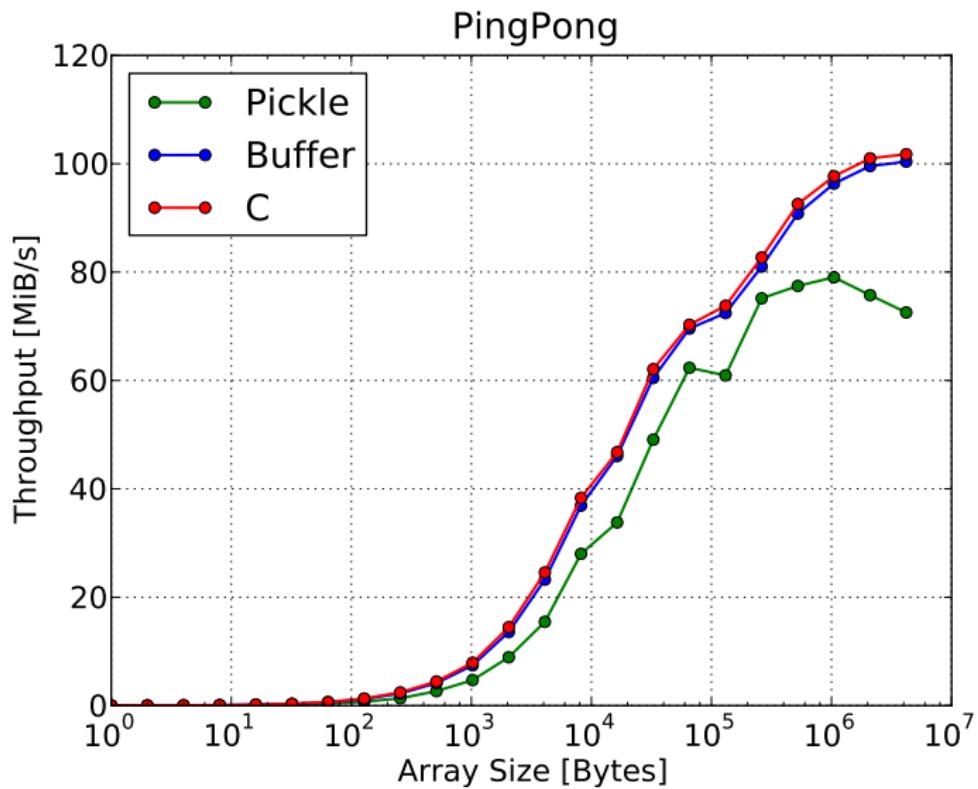


```
<object> ← pickle.load() ← recv()
```

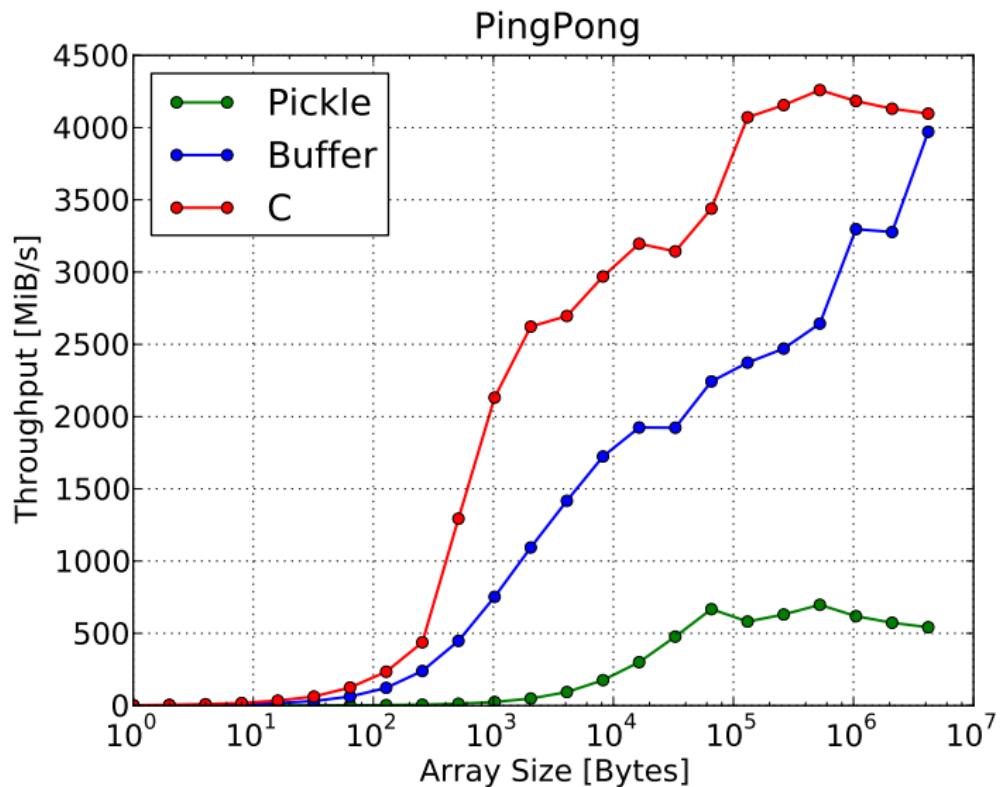
- ▶ Communication of array data (e.g. **NumPy** arrays).
 - ▶ lower level, slightly more verbose
 - ▶ very fast, almost C speed (for messages above 5-10 KB)

```
message = [<object>, (count, displ), datatype]
```

Point to Point Throughput – Gigabit Ethernet



Point to Point Throughput – Shared Memory



Features – IPython

Integration with **IPython** enables MPI to be used *interactively*.

- ▶ Start engines with MPI enabled

```
$ ipcluster mpiexec -n 16 --mpi=mpi4py
```

- ▶ Connect to the engines

```
$ ipython
```

```
In [1]: from IPython.kernel import client
```

```
In [2]: mec = client.MultiEngineClient()
```

```
In [3]: mec.activate()
```

- ▶ Execute commands using %px

```
In [4]: %px from mpi4py import MPI
```

```
In [5]: %px print(MPI.Get_processor_name())
```

Features – Interoperability

Good support for wrapping other MPI-based codes.

- ▶ You can use **Cython** (`cimport` statement).
- ▶ You can use **SWIG** (`typemaps` provided).
- ▶ You can use **F2Py** (`py2f()`/`f2py()` methods).
- ▶ You can use **Boost::Python** or **hand-written C** extensions.

mpi4py will allow you to use virtually any MPI based
C/C++/Fortran code from Python.

Hello World!

```
1 from mpi4py import MPI
2
3 rank = MPI.COMM_WORLD.Get_rank()
4 size = MPI.COMM_WORLD.Get_size()
5 name = MPI.Get_processor_name()
6
7 print ("Hello, World! "
8       "I am process %d of %d on %s" %
9       (rank, size, name))
```

Hello World! – Wrapping with SWIG

C source

```
1 /* file: helloworld.c */
2 void sayhello(MPI_Comm comm)
3 {
4     int size, rank;
5     MPI_Comm_size(comm, &size);
6     MPI_Comm_rank(comm, &rank);
7     printf("Hello, World! "
8            "I am process "
9            "%d of %d.\n",
10           rank, size);
11 }
```

SWIG interface file

```
1 // file: helloworld.i
2 %module helloworld
3 ^{
4     #include <mpi.h>
5     #include "helloworld.c"
6 }%
7
8 %include mpi4py/mpi4py.i
9 %mpi4py_typemap(Comm, MPI_Comm);
10
11 void sayhello(MPI_Comm comm);
```

At the Python prompt ...

```
>>> from mpi4py import MPI
>>> import helloworld
>>> helloworld.sayhello(MPI.COMM_WORLD)
Hello, World! I am process 0 of 1.
```

Hello World! – Wrapping with Boost.Python

```
1 // file: helloworld.cxx
2 #include <boost/python.hpp>
3 #include <mpi4py/mpi4py.h>
4 using namespace boost::python;
5
6 #include "helloworld.c"
7 static void wrap_sayhello(object py_comm) {
8     PyObject* py_obj = py_comm.ptr();
9     MPI_Comm *comm_p = PyMPIComm_Get(py_obj);
10    if (comm_p == NULL) throw_error_already_set();
11    sayhello(*comm_p);
12 }
13
14 BOOST_PYTHON_MODULE(helloworld) {
15     if (import_mpi4py() < 0) return;
16     def("sayhello", wrap_sayhello);
17 }
```

Hello World! – Wrapping with F2Py

Fortran 90 source

```
1 ! file: helloworld.f90
2 subroutine sayhello(comm)
3   use mpi
4   implicit none
5   integer :: comm, rank, size, ierr
6   call MPI_Comm_size(comm, size, ierr)
7   call MPI_Comm_rank(comm, rank, ierr)
8   print *, 'Hello, World! I am process ',rank,' of ',size,'.'
9 end subroutine sayhello
```

At the Python prompt ...

```
>>> from mpi4py import MPI
>>> import helloworld
>>> fcomm = MPI.COMM_WORLD.py2f()
>>> helloworld.sayhello(fcomm)
Hello, World! I am process 0 of 1.
```

Overview

Communicators

Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

Communicators

communicator = process group + communication context

- ▶ Predefined instances

- ▶ COMM_WORLD
- ▶ COMM_SELF
- ▶ COMM_NULL

- ▶ Accessors

- ▶ rank = comm.Get_rank() # or comm.rank
- ▶ size = comm.Get_size() # or comm.size
- ▶ group = comm.Get_group()

- ▶ Constructors

- ▶ newcomm = comm.Dup()
- ▶ newcomm = comm.Create(group)
- ▶ newcomm = comm.Split(color, key)

Communicators – Create()

```
1 from mpi4py import MPI
2
3 comm = MPI.COMM_WORLD
4 group = comm.Get_group()
5
6 newgroup = group.Excl([0])
7 newcomm = comm.Create(newgroup)
8
9 if comm.rank == 0:
10     assert newcomm == MPI.COMM_NULL
11 else:
12     assert newcomm.size == comm.size - 1
13     assert newcomm.rank == comm.rank - 1
14
15 group.Free(); newgroup.Free()
16 if newcomm: newcomm.Free()
```

Communicators – Split()

```
1 from mpi4py import MPI
2
3 world_rank = MPI.COMM_WORLD.Get_rank()
4 world_size = MPI.COMM_WORLD.Get_size()
5
6 if world_rank < world_size//2:
7     color = 55
8     key = -world_rank
9 else:
10    color = 77
11    key = +world_rank
12
13 newcomm = MPI.COMM_WORLD.Split(color, key)
14 # ...
15 newcomm.Free()
```

Exercise #1

- a) Create a new process group containing the processes in the group of COMM_WORLD with **even** rank. Use the new group to create a new communicator.

Tip: use Group.Incl() or Group.Range_incl()

- b) Use Comm.Split() to split COMM_WORLD in two halves.
- ▶ The first half contains the processes with **even** rank in COMM_WORLD. The process rank ordering in the new communication is **ascending**.
 - ▶ The second half contains the processes with **odd** rank in COMM_WORLD. The process rank ordering in the new communication is **descending**.

Overview

Communicators

Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

- ▶ Blocking communication

- ▶ Python objects

```
comm.send(obj, dest=0, tag=0)  
obj = comm.recv(None, src=0, tag=0)
```

- ▶ Array data

```
comm.Send([array, count, datatype], dest=0, tag=0)  
comm.Recv([array, count, datatype], src=0, tag=0)
```

- ▶ Nonblocking communication

- ▶ Python objects

```
request = comm.isend(object, dest=0, tag=0}  
request.Wait()
```

- ▶ Array data

```
req1 = comm.Isend([array, count, datatype], dest=0, tag=0)  
req2 = comm.Irecv([array, count, datatype], src=0, tag=0)  
MPI.Request.Waitall([req1, req2])}
```

PingPong

```
1  from mpi4py import MPI
2  comm = MPI.COMM_WORLD
3  assert comm.size == 2
4
5  if comm.rank == 0:
6      sendmsg = 777
7      comm.send(sendmsg, dest=1, tag=55)
8      recvmsg = comm.recv(source=1, tag=77)
9  else:
10     recvmsg = comm.recv(source=0, tag=55)
11     sendmsg = "abc"
12     comm.send(sendmsg, dest=0, tag=77)
```

PingPing

```
1  from mpi4py import MPI
2  comm = MPI.COMM_WORLD
3  assert comm.size == 2
4
5  if comm.rank == 0:
6      sendmsg = 777
7      target = 1
8  else:
9      sendmsg = "abc"
10     target = 0
11
12 request = comm.isend(sendmsg, dest=target, tag=77)
13 recvmsg = comm.recv(source=target, tag=77)
14 request.Wait()
```

Exchange

```
1  from mpi4py import MPI
2  comm = MPI.COMM_WORLD
3
4  sendmsg = [comm.rank]*3
5  right = (comm.rank + 1) % comm.size
6  left = (comm.rank - 1) % comm.size
7
8  req1 = comm.isend(sendmsg, dest=right)
9  req2 = comm.isend(sendmsg, dest=left)
10 lmsg = comm.recv(source=left)
11 rmsg = comm.recv(source=right)
12
13 MPI.Request.Waitall([req1, req2])
14 assert lmsg == [left] * 3
15 assert rmsg == [right] * 3
```

PingPing with NumPy arrays

```
1  from mpi4py import MPI
2  import numpy
3  comm = MPI.COMM_WORLD
4  assert comm.size == 2
5
6  if comm.rank == 0:
7      array1 = numpy.arange(10000, dtype='f')
8      array2 = numpy.empty(10000, dtype='f')
9      target = 1
10 else:
11     array1 = numpy.ones(10000, dtype='f')
12     array2 = numpy.empty(10000, dtype='f')
13     target = 0
14
15 request = comm.Isend([array1, MPI.FLOAT], dest=target)
16 comm.Recv([array2, MPI.FLOAT], source=target)
17 request.Wait()
```

Exercise #2

- a) Modify *PingPong* example to communicate NumPy arrays.
Tip: use `Comm.Send()` and `Comm.Recv()`
- b) Modify *Exchange* example to communicate NumPy arrays.
Use nonblocking communication for both sending and receiving.
Tip: use `Comm.Isend()` and `Comm.Irecv()`

Overview

Communicators

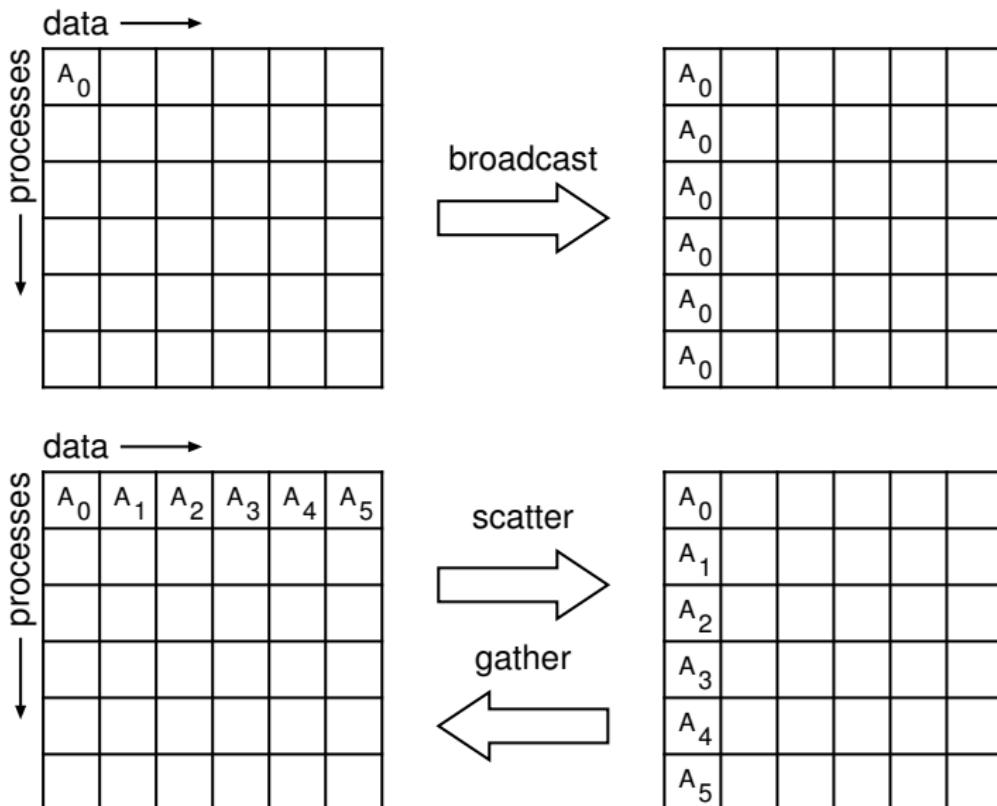
Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

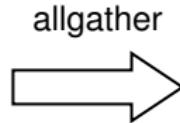
Dynamic Process Management



data →

processes ↓

A ₀					
B ₀					
C ₀					
D ₀					
E ₀					
F ₀					

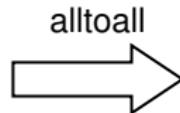


A ₀	B ₀	C ₀	D ₀	E ₀	F ₀
A ₀	B ₀	C ₀	D ₀	E ₀	F ₀
A ₀	B ₀	C ₀	D ₀	E ₀	F ₀
A ₀	B ₀	C ₀	D ₀	E ₀	F ₀
A ₀	B ₀	C ₀	D ₀	E ₀	F ₀
A ₀	B ₀	C ₀	D ₀	E ₀	F ₀

data →

processes ↓

A ₀	A ₁	A ₂	A ₃	A ₄	A ₅
B ₀	B ₁	B ₂	B ₃	B ₄	B ₅
C ₀	C ₁	C ₂	C ₃	C ₄	C ₅
D ₀	D ₁	D ₂	D ₃	D ₄	D ₅
E ₀	E ₁	E ₂	E ₃	E ₄	E ₅
F ₀	F ₁	F ₂	F ₃	F ₄	F ₅



A ₀	B ₀	C ₀	D ₀	E ₀	F ₀
A ₁	B ₁	C ₁	D ₁	E ₁	F ₁
A ₂	B ₂	C ₂	D ₂	E ₂	F ₂
A ₃	B ₃	C ₃	D ₃	E ₃	F ₃
A ₄	B ₄	C ₄	D ₄	E ₄	F ₄
A ₅	B ₅	C ₅	D ₅	E ₅	F ₅

Broadcast

```
1 from mpi4py import MPI
2 comm = MPI.COMM_WORLD
3
4 if comm.rank == 0:
5     sendmsg = (7, "abc", [1.0,2+3j], {3:4})
6 else:
7     sendmsg = None
8
9 recvmsg = comm.bcast(sendmsg, root=0)
```

Scatter

```
1 from mpi4py import MPI
2 comm = MPI.COMM_WORLD
3
4 if comm.rank == 0:
5     sendmsg = [i**2 for i in range(comm.size)]
6 else:
7     sendmsg = None
8
9 recvmsg = comm.scatter(sendmsg, root=0)
```

Gather & Gather to All

```
1 from mpi4py import MPI
2 comm = MPI.COMM_WORLD
3
4 sendmsg = comm.rank**2
5
6 recvmsg1 = comm.gather(sendmsg, root=0)
7
8 recvmsg2 = comm.allgather(sendmsg)
```

Reduce & Reduce to All

```
1 from mpi4py import MPI
2 comm = MPI.COMM_WORLD
3
4 sendmsg = comm.rank
5
6 recvmsg1 = comm.reduce(sendmsg, op=MPI.SUM, root=0)
7
8 recvmsg2 = comm.allreduce(sendmsg)
```

Exercise #3

- a) Modify *Broadcast*, *Scatter*, and *Gather* example to communicate NumPy arrays.
- b) Write a routine implementing parallel *matrix–vector* product
`y = matvec(comm, A, x)`.
 - ▶ the global matrix is dense and square.
 - ▶ matrix rows and vector entries have matching block distribution.
 - ▶ all processes own the same number of matrix rows.

Tip: use `Comm.Allgather()` and `numpy.dot()`

Overview

Communicators

Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

Compute Pi

$$\pi = \int_0^1 \frac{4}{1+x^2} dx \approx \frac{1}{n} \sum_{i=0}^{n-1} \frac{4}{1 + \left(\frac{i+0.5}{n}\right)^2}$$

Compute Pi – sequential

```
1 import math
2
3 def compute_pi(n):
4     h = 1.0 / n
5     s = 0.0
6     for i in range(n):
7         x = h * (i + 0.5)
8         s += 4.0 / (1.0 + x**2)
9     return s * h
10
11 n = 10
12 pi = compute_pi(n)
13 error = abs(pi - math.pi)
14
15 print ("pi is approximately %.16f, "
16       "error is %.16f" % (pi, error))
```

Compute Pi – parallel [1]

```
1  from mpi4py import MPI
2  import math
3
4  def compute_pi(n, start=0, step=1):
5      h = 1.0 / n
6      s = 0.0
7      for i in range(start, n, step):
8          x = h * (i + 0.5)
9          s += 4.0 / (1.0 + x**2)
10     return s * h
11
12 comm = MPI.COMM_WORLD
13 nprocs = comm.Get_size()
14 myrank = comm.Get_rank()
```

Compute Pi – parallel [2]

```
1  if myrank == 0:
2      n = 10
3  else:
4      n = None
5
6  n = comm.bcast(n, root=0)
7
8  mypi = compute_pi(n, myrank, nprocs)
9
10 pi = comm.reduce(mypi, op=MPI.SUM, root=0)
11
12 if myrank == 0:
13     error = abs(pi - math.pi)
14     print ("pi is approximately %.16f, "
15           "error is %.16f" % (pi, error))
```

Exercise #4

Modify *Compute Pi* example to employ NumPy.

Tip: you can convert a Python int/float object to a NumPy scalar with `x = numpy.array(x)`.

Overview

Communicators

Point to Point Communication

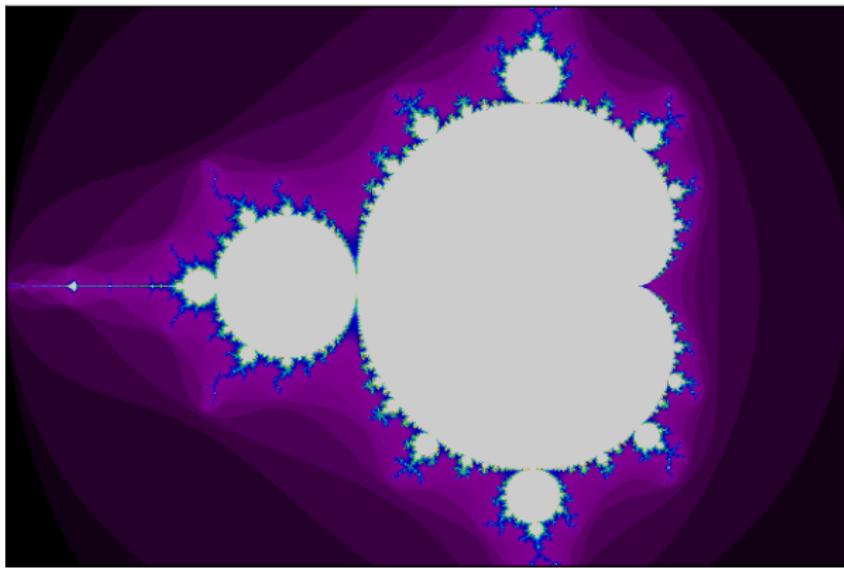
Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

Mandelbrot Set



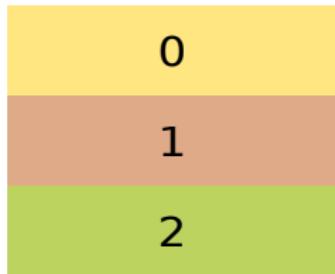
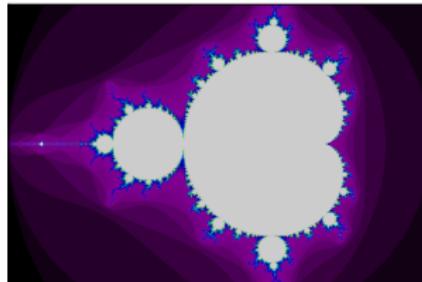
Mandelbrot Set – sequential [1]

```
1 def mandelbrot(x, y, maxit):
2     c = x + y*1j
3     z = 0 + 0j
4     it = 0
5     while abs(z) < 2 and it < maxit:
6         z = z**2 + c
7         it += 1
8     return it
9
10 x1, x2 = -2.0, 1.0
11 y1, y2 = -1.0, 1.0
12 w, h = 150, 100
13 maxit = 127
```

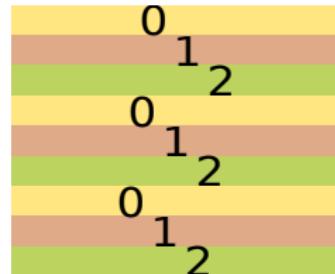
Mandelbrot Set – sequential [2]

```
1 import numpy
2 C = numpy.zeros([h, w], dtype='i')
3 dx = (x2 - x1) / w
4 dy = (y2 - y1) / h
5 for i in range(h):
6     y = y1 + i * dy
7     for j in range(w):
8         x = x1 + j * dx
9         C[i, j] = mandelbrot(x, y, maxit)
10
11 from matplotlib import pyplot
12 pyplot.imshow(C, aspect='equal')
13 pyplot.spectral()
14 pyplot.show()
```

Mandelbrot Set – partitioning



Block distribution



Cyclic distribution

Mandelbrot Set – parallel, block [1]

```
1 def mandelbrot(x, y, maxit):
2     c = x + y*1j
3     z = 0 + 0j
4     it = 0
5     while abs(z) < 2 and it < maxit:
6         z = z**2 + c
7         it += 1
8     return it
9
10 x1, x2 = -2.0, 1.0
11 y1, y2 = -1.0, 1.0
12 w, h = 150, 100
13 maxit = 127
```

Mandelbrot Set – parallel, block [2]

```
1 from mpi4py import MPI
2 import numpy
3
4 comm = MPI.COMM_WORLD
5 size = comm.Get_size()
6 rank = comm.Get_rank()
7
8 # number of rows to compute here
9 N = h // size + (h % size > rank)
10
11 # first row to compute here
12 start = comm.scan(N)-N
13
14 # array to store local result
15 C1 = numpy.zeros([N, w], dtype='i')
```

Mandelbrot Set – parallel, block [3]

```
1 # compute owned rows
2
3 dx = (x2 - x1) / w
4 dy = (y2 - y1) / h
5 for i in range(N):
6     y = y1 + (i + start) * dy
7     for j in range(w):
8         x = x1 + j * dx
9         C1[i, j] = mandelbrot(x, y, maxit)
```

Mandelbrot Set – parallel, block [4]

```
1 # gather results at root (process 0)
2
3 counts = comm.gather(N, root=0)
4 C = None
5 if rank == 0:
6     C = numpy.zeros([h, w], dtype='i')
7
8 rowtype = MPI.INT.Create_contiguous(w)
9 rowtype.Commit()
10
11 comm.Gatherv(sendbuf=[C1, MPI.INT],
12                 recvbuf=[C, (counts, None), rowtype],
13                 root=0)
14
15 rowtype.Free()
```

Mandelbrot Set – parallel, block [5]

```
1 if comm.rank == 0:  
2     from matplotlib import pyplot  
3     pyplot.imshow(C, aspect='equal')  
4     pyplot.spectral()  
5     pyplot.show()
```

Exercise #5

Measure the wall clock time T_i of local computations at each process for the *Mandelbrot Set* example with **block** and **cyclic** row distributions.

What row distribution is better regarding load balancing?

Tip: use `Wtime()` to measure wall time, compute the ratio T_{\max}/T_{\min} to compare load balancing.

Overview

Communicators

Point to Point Communication

Collective Operations

Compute Pi

Mandelbrot Set

Dynamic Process Management

Dynamic Process Management

- ▶ Useful in assembling complex distributed applications. Can couple **independent parallel codes** written in **different languages**.
- ▶ Create new processes from a running program.
 - Comm.Spawn() and Comm.Get_parent()
- ▶ Connect two running applications together.
 - Comm.Connect() and Comm.Accept()

Dynamic Process Management – Spawning

Spawning new processes is a *collective operation* that creates an **intercommunicator**.

- ▶ Local group is group of spawning processes (parent).
- ▶ Remote group is group of new processes (child).
- ▶ `Comm.Spawn()` lets parent processes spawn the child processes. It returns a new intercommunicator.
- ▶ `Comm.Get_parent()` lets child processes find intercommunicator to the parent group. Child processes have own `COMM_WORLD`.
- ▶ `Comm.Disconnect()` ends the parent–child connection. After that, both groups can continue running.

Dynamic Process Management – Compute Pi (parent)

```
1 from mpi4py import MPI
2 import sys, numpy
3
4 comm = MPI.COMM_SELF.Spawn(sys.executable,
5                             args=['compute_pi-child.py'],
6                             maxprocs=5)
7
8 N = numpy.array(10, 'i')
9 comm.Bcast([N, MPI.INT], root=MPI.ROOT)
10 PI = numpy.array(0.0, 'd')
11 comm.Reduce(None, [PI, MPI.DOUBLE],
12              op=MPI.SUM, root=MPI.ROOT)
13 comm.Disconnect()
14
15 error = abs(PI - numpy.pi)
16 print ("pi is approximately %.16f, "
17        "error is %.16f" % (PI, error))
```

Dynamic Process Management – Compute Pi (child)

```
1 from mpi4py import MPI
2 import numpy
3
4 comm = MPI.Comm.Get_parent()
5 size = comm.Get_size()
6 rank = comm.Get_rank()
7
8 N = numpy.array(0, dtype='i')
9 comm.Bcast([N, MPI.INT], root=0)
10 h = 1.0 / N; s = 0.0
11 for i in range(rank, N, size):
12     x = h * (i + 0.5)
13     s += 4.0 / (1.0 + x**2)
14 PI = numpy.array(s * h, dtype='d')
15 comm.Reduce([PI, MPI.DOUBLE], None,
16             op=MPI.SUM, root=0)
17
18 comm.Disconnect()
```

Exercise #5

- a) Implement the *Compute Pi* **child** code in **C** or **C++**. Adjust the parent code in Python to spawn the new implementation.
- b) Compute and plot the *Mandelbrot Set* using spawning with parent/child codes implemented in Python.

Tip: Reuse the provided parent code in Python and translate the child code in Fortran 90 to Python.

Do not hesitate to ask for help ...

- ▶ Mailing List: mpi4py@googlegroups.com
- ▶ Mail&Chat: dalcinl@gmail.com

Thanks!